

Theoretical study of variational inference

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RIKEN AIP Seminar
February 20, 2020

- 1 Basics of variational inference
 - Tempered posteriors
 - Variational approximations
 - Challenges in VI theory
- 2 Consistency of variational inference
 - Posterior consistency
 - Theoretical results
 - Example
- 3 Online variational inference algorithms
 - Bayes & online learning
 - Online variational inference
 - Simulations

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Notations

Assume that we observe X_1, \dots, X_n i.i.d from P_{θ_0} in a model $\{P_{\theta}, \theta \in \Theta\}$ dominated by $Q : \frac{dP_{\theta}}{dQ} = p_{\theta}$. Prior π on Θ .

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The tempered posterior - $0 < \alpha < 1$

$$\pi_{n,\alpha}(d\theta) \propto [L_n(\theta)]^{\alpha}\pi(d\theta).$$

Various reasons to use a tempered posterior

- Easier to sample from



G. Behrens, N. Friel & M. Hurn. (2012). Tuning tempered transitions. *Statistics and Computing*.

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- Theoretical analysis easier



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We have the equivalent definition :

$$\tilde{\pi}_{n,\alpha} := \arg \max_{\rho \in \mathcal{F}} \text{ELBO}(\rho)$$

with

$$\text{ELBO}(\rho) = \alpha \int \frac{1}{n} \sum_{i=1}^n \log p_{\theta}(X_i) \rho(d\theta) - KL(\rho, \pi).$$

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We will see that fast algorithms from online optimization can be used to compute online variational approximations.

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Tools for the consistency of VB

The α -Rényi divergence for $\alpha \in (0, 1)$

$$D_\alpha(P, R) = \frac{1}{\alpha - 1} \log \int (dP)^\alpha (dR)^{1-\alpha}.$$

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$$D_\alpha(P, R) = \frac{1}{\alpha - 1} \log \int (dP)^\alpha (dR)^{1-\alpha}.$$

All the properties derived in :



T. Van Erven & P. Harremoës. Rényi divergence and Kullback-Leibler divergence. *IEEE Transactions on Information Theory*, 2014.

Among others, for $1/2 \leq \alpha$, link with Hellinger and Kullback :

$$\mathcal{H}^2(P, R) \leq D_\alpha(P, R) \xrightarrow{\alpha \nearrow 1} KL(P, R).$$

Notions of Concentration and Consistency

Concentration at rate r_n

$$\rho\left(\theta \in \Theta / D_\alpha(P_\theta, P_{\theta_0}) > M_n r_n\right) \xrightarrow[n \rightarrow +\infty]{} 0$$

in probability as $n \rightarrow +\infty$ for any $M_n \rightarrow +\infty$.

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Consistency implies concentration of the Bayesian distribution.

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Technical condition for posterior concentration

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Prior mass condition for concentration of tempered posteriors

The rate (r_n) is such that

$$\pi[\mathcal{B}(r_n)] \geq e^{-nr_n}$$

where $\mathcal{B}(r) = \{\theta \in \Theta : KL(P_{\theta^0}, P_{\theta}) \leq r\}$.

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Prior mass condition for concentration of Variational Bayes

The rate (r_n) is such that there exists $\rho_n \in \mathcal{F}$ such that

$$\int KL(P_{\theta^0}, P_{\theta}) \rho_n(d\theta) \leq r_n, \quad \text{and} \quad KL(\rho_n, \pi) \leq nr_n.$$

What do we know about $\pi_{n,\alpha}$?

Theorem, variant of (Bhattacharya, Pati & Yang)

Under the prior mass condition, for any $\alpha \in (0, 1)$,

$$\mathbb{E} \left[\int D_{\alpha}(P_{\theta}, P_{\theta_0}) \pi_{n,\alpha}(d\theta) \right] \leq \frac{1 + \alpha}{1 - \alpha} r_n.$$



A. Bhattacharya, D. Pati & Y. Yang. Bayesian fractional posteriors. *The Annals of Statistics*, 2019.

Extension of previous result to VB

Theorem (Alquier & Ridgway)

Under the extended prior mass condition, for any $\alpha \in (0, 1)$,

$$\mathbb{E} \left[\int D_{\alpha}(P_{\theta}, P_{\theta_0}) \tilde{\pi}_{n,\alpha}(\mathrm{d}\theta) \right] \leq \frac{1 + \alpha}{1 - \alpha} r_n.$$



P. Alquier & J. Ridgway. Concentration of tempered posteriors and of their variational approximations. *The Annals of Statistics*, 2019.

Misspecified case

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Theorem (Alquier and Ridgway)

Under a similar condition, for any $\alpha \in (0, 1)$,

$$\mathbb{E} \left[\int D_\alpha(P_\theta, Q) \tilde{\pi}_{n,\alpha}(d\theta) \right] \leq \frac{\alpha}{1 - \alpha} \inf_{\theta} KL(Q, P_\theta) + \frac{1 + \alpha}{1 - \alpha} r_n.$$

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Nonparametric regression & Deep Neural Networks

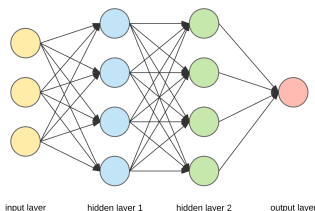
Nonparametric regression

- $X_i \sim \mathcal{U}([-1, 1]^d)$,
- $Y_i = f_0(X_i) + \zeta_i$,
- $\zeta_i \sim \mathcal{N}(0, \sigma^2)$.

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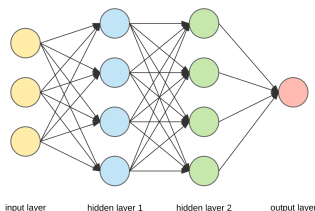
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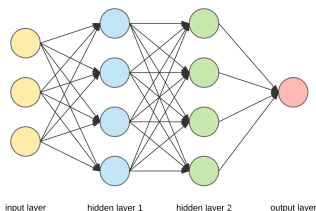
Deep neural networks

- Depth $L \geq 3$, width $D \geq d$, sparsity $S \leq T$.

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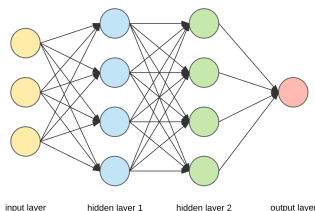
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- Parameter $\theta = \{(A_1, b_1), \dots, (A_L, b_L)\}$.
- $f_\theta(x) = A_L \rho(A_{L-1} \dots \rho(A_1 x + b_1) + \dots + b_{L-1}) + b_L$.

ReLU Deep Neural Networks : convergence rates

Theorem (C.-A.)

Chose spike-and-slab prior and variational set on θ .

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$$\begin{aligned} \mathbb{E} \left[\int \|f_\theta - f_0\|_2^2 \tilde{\pi}_{n,\alpha}(d\theta) \right] \\ \leq \frac{2}{1-\alpha} \inf_{\theta^*} \|f_{\theta^*} - f_0\|_2^2 + \frac{2}{1-\alpha} \left(1 + \frac{\sigma^2}{\alpha} \right) r_n^{S,L,D}, \end{aligned}$$

with $r_n^{S,L,D} \sim \frac{S \log(nL/S)}{n} \vee \frac{LS \log D}{n}$.

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C.-A.. Convergence Rates of Variational Inference in Sparse Deep Learning. *Preprint Arxiv*, 2019.

More extensions

1 more general models with latent variables :



Y. Yang, D. Pati & A. Bhattacharya. α -Variational Inference with Statistical Guarantees. *The Annals of Statistics*, 2019.

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- 3 approximation based on another distance, for example :

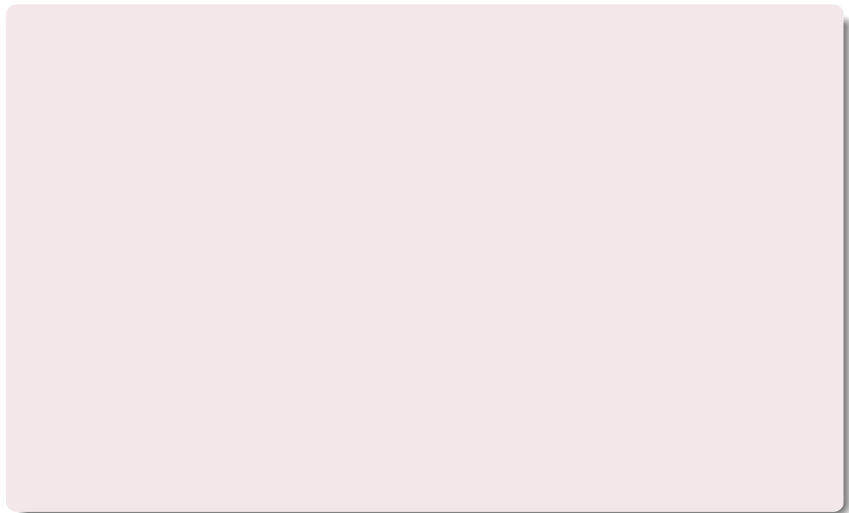
$$\tilde{\pi}_{n,\alpha} := \arg \min_{\rho \in \mathcal{F}} \mathcal{W}(\rho, \pi_{n,\alpha}) \text{ (Wasserstein distance),}$$



J. Huggins, T. Campbell, M. Kasprzak & T. Broderick. Practical bounds on the error of Bayesian posterior approximations : a nonasymptotic approach. *Preprint arXiv*, 2018.

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Online optimization



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Objective : make sure that we learn to predict well as fast as possible.

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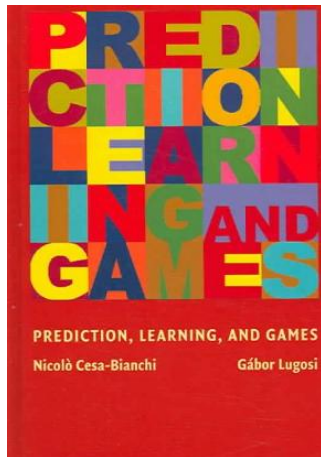
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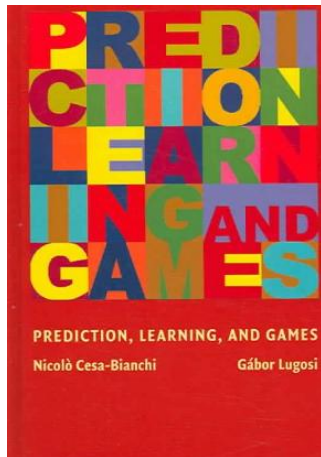
$$\sum_{t=1}^T \ell(x_t; \theta_t)$$

as small as possible for any T ,
without stochastic assumptions on the data.

Reference



Reference



The regret :

$$\begin{aligned} R(T) &= \sum_{t=1}^T \ell(x_t; \theta_t) \\ &\quad - \inf_{\theta \in \Theta} \sum_{t=1}^T \ell(x_t; \theta). \end{aligned}$$

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- Loss $\ell_t(\theta) := \ell(x_t; \theta)$.
- Initialize θ_1 .
- Update $\theta_{t+1} = \theta_t - \alpha \nabla_{\theta} \ell_t(\theta_t)$.
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- **Equivalent online formulation for VI?**

A regret bound for EWA

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Theorem

If the loss is bounded by B :

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim \pi_{t,\alpha}} [l_t(\theta)] \leq \inf_q \left\{ \sum_{t=1}^T \mathbb{E}_{\theta \sim q} [l_t(\theta)] + \frac{\alpha B^2 T}{8} + \frac{KL(q, \pi)}{\alpha} \right\}.$$

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Under similar assumptions than in the batch case, that is, the prior gives enough mass to relevant θ , and $\alpha \sim 1/\sqrt{T}$,

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Equivalent regret bounds for VI ?

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Variational approximations of EWA



B.-E. Chérif-Abdellatif, P. Alquier & M. E. Khan. A Generalization Bound for Online Variational Inference. *Proceedings of ACML*, 2019.

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Parametric variational approximation :

$$\mathcal{F} = \{q_{\mu}, \mu \in M\}.$$

Objective : propose a way to update $\mu_t \rightarrow \mu_{t+1}$ so that q_{μ_t} leads to similar performances as $\pi_{t,\alpha}$ in EWA...

SVA and SVB strategies

- SVA (Sequential Variational Approximation) :

$$\mu_{t+1} = \arg \min_{\mu \in M} \left\{ \sum_{s=1}^t \mathbb{E}_{\theta \sim q_{\mu}} [\ell_s(\theta)] + \frac{KL(q_{\mu}, \pi)}{\alpha} \right\}.$$

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SVA and SVB strategies

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An example : SVB with Gaussian approximations

As an example, assume that $\theta \in \mathbb{R}^d$, the prior is $\pi = \mathcal{N}(0, s^2 I)$ and that we use the variational approximation

$$\text{family : } q_{\mu} = q_{m, \sigma} = \mathcal{N} \left(m, \begin{pmatrix} \sigma_1^2 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_d^2 \end{pmatrix} \right).$$

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In this case, the update in SVB is :

$$\begin{aligned} m_{t+1} &= m_t - \alpha \sigma_t^2 \odot \nabla_{m=m_t} \mathbb{E}_{\theta \sim q_{m_t, \sigma_t}} [\ell_t(\theta)] \\ \sigma_{t+1} &= \sigma_t \odot h \left(\frac{\alpha \sigma_t \nabla_{\sigma=\sigma_t} \mathbb{E}_{\theta \sim q_{m_t, \sigma}} [\ell_t(\theta)]}{2} \right) \end{aligned}$$

where \odot means “componentwise multiplication” and $h(x) = \sqrt{1 + x^2} - x$ is also applied componentwise.

A regret bound for SVA

Theorem (C.A., Alquier & Khan)

Assume that the expected loss is L -Lipschitz and convex.

A regret bound for SVA

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Assume that the expected loss is L -Lipschitz and convex. (this is for example the case as soon as the loss is convex in θ and L -Lipschitz, and μ is a location-scale parameter).

A regret bound for SVA

Theorem (C.A., Alquier & Khan)

Assume that the expected loss is L -Lipschitz and convex.
Assume that $\mu \mapsto KL(q_\mu, \pi)$ is γ -strongly convex. Then SVA satisfies :

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim q_{\mu_t}} [\ell_t(\theta)] \leq \inf_{\mu} \left\{ \sum_{t=1}^T \mathbb{E}_{\theta \sim q_{\mu}} [\ell_t(\theta)] + \frac{\alpha L^2 T}{\gamma} + \frac{KL(q_{\mu}, \pi)}{\alpha} \right\}.$$

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Application to Gaussian approximation leads to :

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim q_{\mu_t}} [\ell_t(\theta)] \leq \inf_{\theta} \sum_{t=1}^T \ell_t(\theta) + (1 + o(1)) \frac{2L}{\gamma} \sqrt{dT \log(T)}.$$

For SVB : some results in the Gaussian case.

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Test on the Forest Cover Type dataset

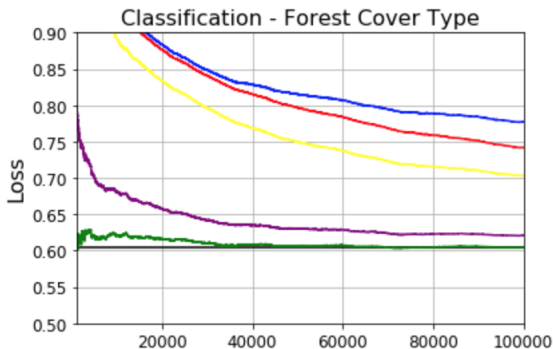


Figure – Average cumulative losses on different datasets for classification and regression tasks with OGA (yellow), OGA-EL (red), SVA (blue), SVB (purple) and NGVI (green).

Test on the Boston Housing dataset

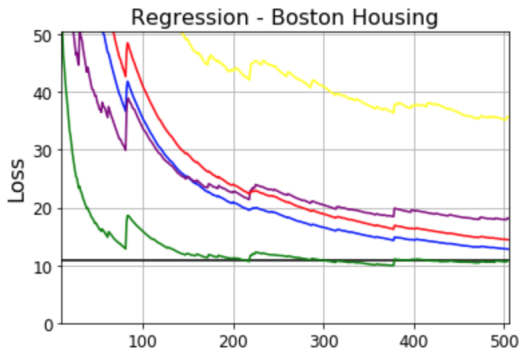


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Final remarks (1)

Using online-to-batch conversion, we can have algorithms for variational inference with provable statistical properties.

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Final remarks (2)

NGVI (Natural Gradient Variational Inference) : fix some $\beta > 0$,

$$\mu_{t+1} = \arg \min_{\mu \in M} \left\{ \mu^T \nabla_{\mu=\mu_t} \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)] + \frac{KL(q_\mu, \pi)}{\alpha} + \frac{KL(q_\mu, q_{\mu_t})}{\beta} \right\}.$$

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M. E. Khan & W. Lin. Conjugate-computation variational inference : Converting variational inference in non-conjugate models to inferences in conjugate models. *AISTAT*, 2017.

NGVI is the best method on all datasets. Its theoretical analysis is thus an important open problem. Cannot be done with our current techniques (using natural parameters in exponential models lead to non-convex objectives).

Thank you !